

Project ANR McBIM

Deliverable 2.2

Prototypes of Sensing and Communicating Nodes for a
Wireless Sensor Network Embedded in Reinforced Concrete

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I. INTRODUCTION

With the rise of technologies dedicated to the Internet of Things (IoT), the Wireless Sensor Networks (WSN) are more and more performant, diversified and common. These last can be used in order to implement Cyber-Physical Systems (CPS) to monitor and/or command some physical objects. This is especially the case for Structural Health Monitoring (SHM) applications, for instance of concrete civil structures [1-2]. Moreover, and in order to make these systems fully wireless and offer an expanded lifespan, ambient Energy Harvesting (EH) (e.g. photovoltaic, thermal, mechanical, etc.) and Wireless Power Transmission (WPT) solutions are investigated and developed [3-4]. In this context, the McBIM project (Material communicating with the Building Information Modelling (BIM)) -funded by the French National Research Agency (ANR)- tends to propose an implementation of the concept of communicating materials in the construction domain and more specifically by developing a communicating reinforced concrete [5]. This one must be intrinsically able to generate, store -locally and remotely-, process and exchange data -from its own health and/or environment- with other communicating components and with virtual models -as BIM- through the Internet.

Subsequently, the presentation of the McBIM project will be more detailed. Then, the WSN hardware design developed for the implementation of a communicating concrete will be presented, as well as the experimental results achieved to date and providing a full proof-of-concept. Before to conclude, some critical analysis will be proposed in order to explicit current and future works and the contributions of this research.

II. THE MCBIM PROJECT

In order to provide a communicating reinforced concrete linked to an evolutive BIM, a consortium of three French laboratories and one company was set up. Each one has its own role. The LAAS-CNRS (Toulouse) has to implement the hardware part of the communicating reinforced concrete by developing a devoted WSN -this is the purpose of this paper-. The CRAN (Nancy) works on the data collection protocols in the network of communicating reinforced concrete components in order to extend their lifetime by minimizing their energy consumption and need of maintenance, while ensuring their resilience and assuring their scalability [6]. The LIB (Dijon) trades with the data exchanges and the data integration within BIM platforms by respecting the current standards [7]. Finally, FINAO SAS/360SmartConnect (Trans-en-Provence) prospects building and civil engineering companies to get various real-life use cases, as well as providing reinforced concrete elements to do experiments [8].

The targeted communicating reinforced concrete must meet some constraints. First of all, it must be useful during all its lifecycle: from its manufacture and storage (in the case of precast elements), to its

recycling, through the construction of a complete structure based on a combination of elements, as well as the exploitation of this structure, particularly for SHM applications. Thus, its lifespan can be estimated in terms of decades. Then, the communicating reinforced concrete must be scalable in terms of format (e.g. fluid screeds, precast elements for a wall, a bridge deck, etc.) and evolutive during the time in terms of data (type, quantity and periodicity). Indeed, the need in data is function of the step in the lifecycle. For the manufacture, the hourly monitoring of the temperature and humidity evolution during the curing process can help in the decision to continue or not the works (e.g. to un mould a precast element, to tile a floor, etc.). For the storage or the shipping of precast elements and for the construction of a structure, there are the logistic aspects which are the more important, as the ID of elements, their current owner, their location, their delivery address, in which project they must be used, other elements in their neighbourhood, etc. It is also conceivable to create a precise and real-time plan of a structure during its construction, whilst also continuously sharing information between all the stakeholders by using the data stored locally in the element and/or in the BIM. For the exploitation phase, SHM applications are relevant and diverse: the monitoring of temperature and humidity could give information about maturity; the monitoring of the temperature at each side of a wall could be used to quantify its real thermal resistance and certify standards; the cracks detection could allow the application of preventive treatment to avoid irreversible damages and collapses, etc. Thus, with a unique communicating reinforced concrete, different applications can be processed during the entire lifespan of elements by using specific sensors at specific periodicities.

III. DESIGN OF THE WIRELESS SENSOR NETWORK

With the aim of providing a hardware implementation of a communicating reinforced concrete, the choice of the use of a WSN embedded in reinforced concrete for decades was made. In that way, it became possible to render the reinforced concrete intrinsically able to sense its own properties -or these from its environment-, to process, store locally and exchange this data with other communicating materials and with virtual models through the Internet. It also becomes a full CPS.

A. *Architecture of the Wireless Sensor Network*

The designed WSN -presented in Fig. 1- allows to produce, process, store and exchange data from the physical world to the physical world (e.g. other communicating materials, owner, user or other stakeholder devices, etc.) and to the digital world through the Internet (e.g. BIM, owner, user or other stakeholder information systems, etc.).

This WSN is composed of two kinds of smart nodes: the Sensing Nodes (SN) and the Communicating Nodes (CN). The SN make measurements, pre-process the collected data and send them to the CN. The CN collect the data sent by the SN, process and store them. They exchange this data with other CN constituting the WSN and with other WSN, and virtual models -as BIM- through the Internet. They are

reachable through the devices of the owners, users or other stakeholders. Finally, the CN can wirelessly supply the SN. Each component of communicating reinforced concrete embed a number of SN and CN function of its size and its needs (e.g. kinds of sensor, desired spatial precision, etc.).

LoRa wireless technology and LoRaWAN protocol in the European ISM 868 MHz band were chosen as communication solution between SN and CN [9]. Indeed, it seemed to be a relatively low energy consumption way to get long range unidirectional communication. Moreover, a wideband signal (through Chirp Spread Spectrum (CSS) technique) seemed less sensitive to the noise induced by the reinforced concrete which appears very binding for electromagnetic waves. Nevertheless, less consuming and medium range technologies as IEEE 802.15.1 Bluetooth Low Energy (BLE) [10] or IEEE 1902.1 RuBEE [11] are considered for next developments.

As common ambient energy sources are not usable inside reinforced concrete (i.e. there is no light radiation for photovoltaic, there is locally no sufficient gradient of temperature for thermal solutions, natural vibrations of concrete structure are too low for compact mechanical solutions, ambient radiofrequency (RF) energy is too low for RF EH [4]), the RF WPT seemed to be relevant to have a control way to wirelessly supply the SN by the CN. To have a greater operating distance, the far-field (radiative) solution was preferred to the near-field (inductive) one. Finally, the choice of the European ISM 868 MHz band was driven by a comprised between antenna size and losses in free space.

By using the same frequency band for the wireless communication and power transmission, an implemented and tested solution for Simultaneous Wireless Information and Power Transmission (SWIPT) paradigm is provided [12].

B. Design of the Communicating Nodes

The communicating nodes -presented in Fig. 2- must be able to gather, process and store the data sent by the SN, as well as share these with other CN, other WSN, stakeholders and digital models through the Internet to update them. They are the energy suppliers of the SN through far-field RF WPT.

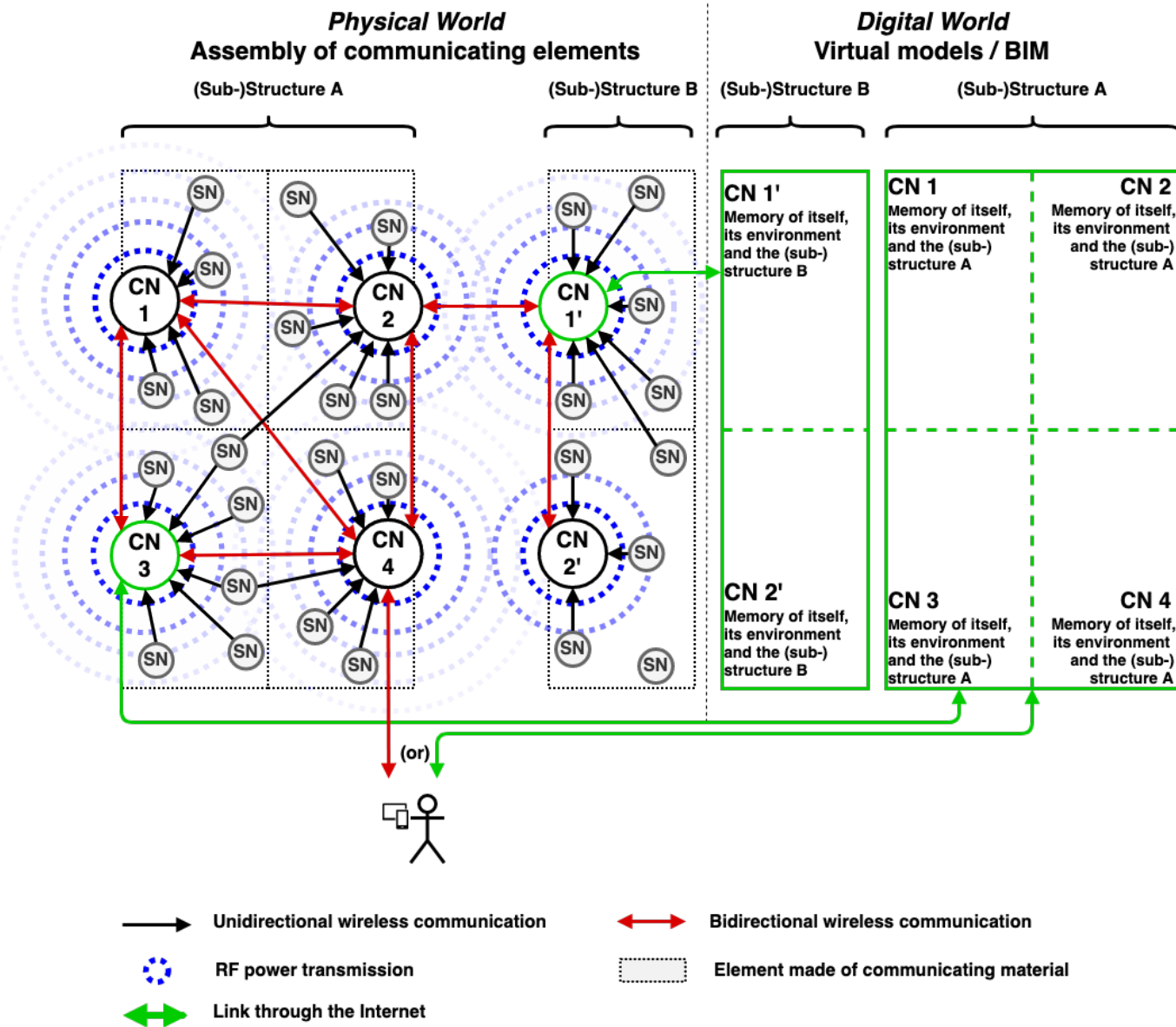


Fig. 1. Bloc diagram of the architecture of the cyber-physical system composing the communicating reinforced concrete.

To achieve these tasks, the current CN are composed of a LoRaWAN gateway and a RF power source.

The LoRaWAN gateway embeds a LoRa Server and consists of a Raspberry Pi 3 model B+ micro-computer -with a Linux OS- connected to an IMST iC880A LoRaWAN concentrator for European ISM 868 MHz band. Thanks to software, this one collects, processes and stores the data sent by SN and can access to the Internet and digital world, and be accessed by stakeholders, through an Ethernet or Wi-Fi link.

The RF power source is made of Mini-Circuits components and provides the maximal allowed RF power in the European ISM 868 MHz band of +33 dBm EIRP (or 2 W) [13]. This one allows to wirelessly power the SN.

c. Design of the Sensing Nodes

The sensing nodes -presented in Fig. 2- must sense some parameters from their internal state or their environment and wirelessly send the measured data to the CN. The SN become inaccessible once deployed in the reinforced concrete, thus, these must be reliable, usable for decades by being energy autonomous and battery-free.

The current SN consist of two parts: one dedicated to the power supply and one to the collect and transmission of data.

For the power supply, a rectenna (for rectifying antenna) developed in our team is used to collected RF power transmitted by the CN and to convert it into electrical power [14]. This dc power is then managed by a Texas Instruments bq25504 Power Management Unit (PMU) which stores it into an AVX BZ01CA223ZSB 22 mF supercapacitor. When enough energy is harvested, the stored energy is used to supply the part dedicated to collect and transmit the data, through a Texas Instruments TPS63031 dc-to-dc buck-boost converter.

For the collect and transmission of the data, a Texas Instruments HDC2010 temperature and humidity sensor achieves the measurement, then the collected data is processed and transmitted by a Murata CMWX1ZZABZ-091 all-in-one LoRaWAN module -which embeds a STMicroelectronics STM32L0 microcontroller and a Semtech SX1276 transceiver- and a meandered monopole antenna.

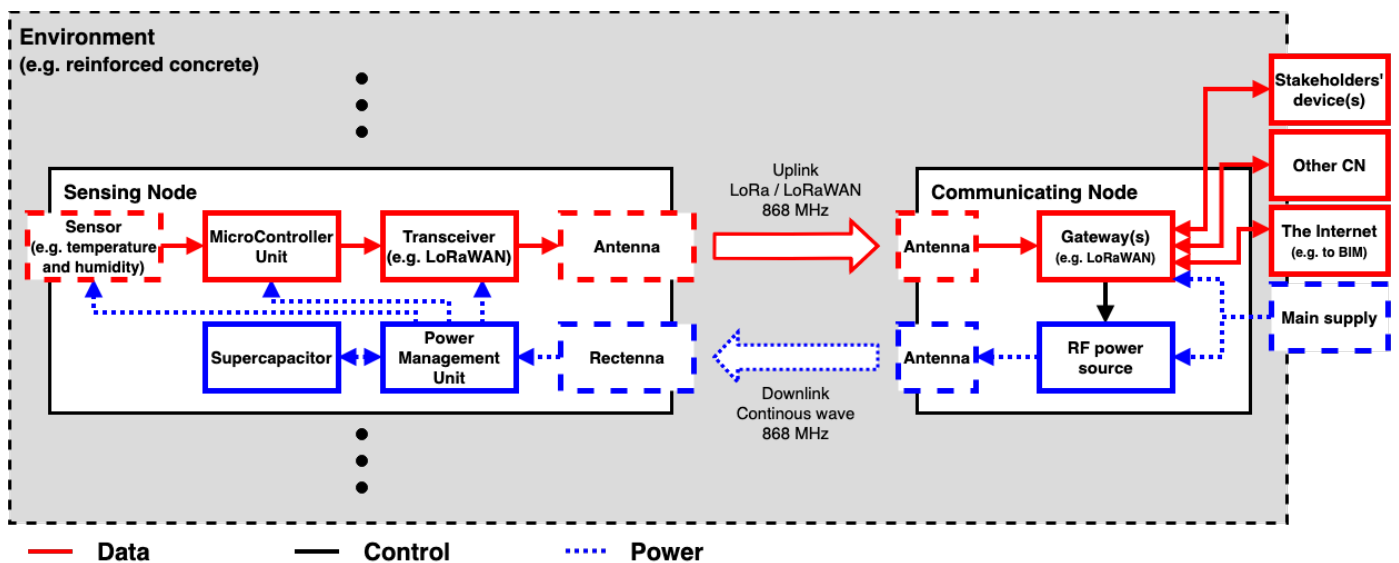


Fig. 2. Bloc diagrams of the sensing nodes and communicating nodes.

IV. EXPERIMENTAL RESULTS

To certify the proper functioning of our system, several tests -both qualitative and quantitative- have been carried out.

A. Communicating Nodes

In their current version presented in Fig. 9. C., the communicating nodes are able to receipt the data sent by the SN, as well as process and store it, before make it available to their owner thanks to an Ethernet or Wi-Fi interface, or through the Internet. In addition, they can wirelessly power over several meters many SN located in their neighbourhood.

To provide a Continuous Wave (CW) signal at 868 MHz with a +33 dBm EIRP power, the RF power source need nearly 4.45 W of power with a 12 V voltage. As well, the LoRaWAN gateway need between 4.0 W and 4.8 W of power with a 5 V voltage to work properly. The amount of needed power is function of its state (standby, processing or reception) and of the connection with other devices (without, through Ethernet or through Wi-Fi). Thus, in the worst case, a 1 Ah battery allows to continuously power the CN for nearly 45 minutes, and a battery of nearly 32 Ah is needed to power it for 24h. In order to release constraints during the development phase, the CN are also accessible and powered by the main supply.

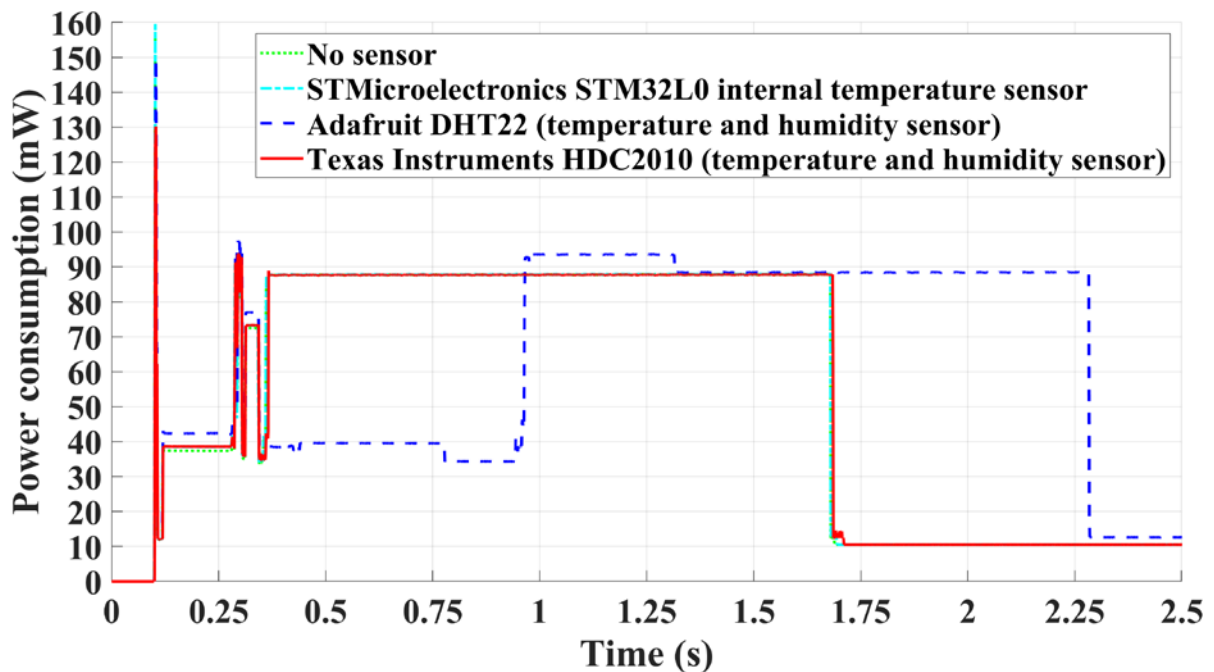


Fig. 3. Consumption of the sensing nodes with various sensors (SN is powered at 3.3 V from Time = 0.1 s).

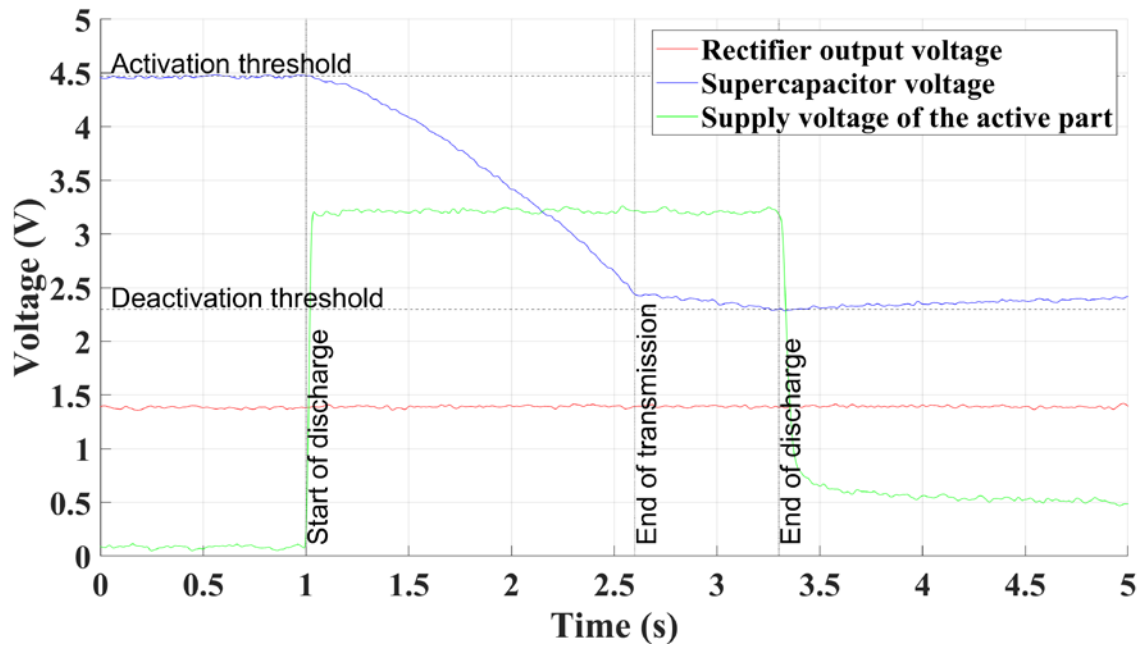


Fig. 4. Use of the stored energy by the sensing nodes with a +10 dBm RF power available at the input of the rectifier.

Even if the current version of the CN is composed of two distinct sub-systems: the LoRaWAN gateway and the RF power source; with various useful distances in the air: respectively kilometres and meters; these two elements can be located at the same place without communication losses. To go further, preliminary tests with the use of an Aerotek C11-1FFF/OPT.N circulator between a monopole antenna (port 1), the LoRaWAN gateway input (port 2) and the RF power source output (port 3) were successfully performed: a SN at 60 cm and 160 cm from the antenna has been wirelessly powered by the CN and transmitted all its measured data to the CN.

B. Sensing Nodes

In their current version presented in Fig. 9. B., the sensing nodes allow to monitor temperature and humidity of their near environment and to transmit this data once pre-processed over several kilometres thanks to LoRa technology and LoRaWAN protocol. Furthermore, their energy autonomy is assured by a far-field RF WPT technique which wirelessly powers them over several meters. Besides, the periodicity of measurement and communication can be remotely control through the command of the WPT system.

From the SN presented in [15], several improvements were achieved.

First, a more precise temperature and humidity sensor consuming less time (1.6 s instead of 2.13 s for the entire process -measurement and transmission-) and also energy (130 mJ instead of 171 mJ) is used as presented in Fig. 3. Also, by using a dc-to-dc buck-boost converter the energy consumption of the active part is reduced too (by limiting the losses due to higher voltages). Thus, even if the capacity could not have been reduced (22 mF), less energy is needed by the SN (from 214 mJ to 150 mJ) and by reducing the

activation (from 5.25 V to 4.45 V) and deactivation (from 2.35 V to 2.30 V) threshold voltages as shown in Fig. 4, less energy is stored (from 245 mJ to 159 mJ, always with extra energy), which allows shorter time for recharge.

What is more, different rectifiers were characterized with the SN. A doubler RF rectifier manufactured on 0.8 mm thick FR4 substrate (Rect1) [14], a compact (1 cm x 2 cm) serial half-wave RF rectifier manufactured on 1.6 mm thick FR4 substrate (Rect2) and a serial half-wave RF rectifier manufactured on 0.8 mm thick Rogers Duroid 5870 substrate (Rect3) [16] -all based on Schottky diodes- were studied and compared for powering the SN. Fig. 5 shows the times needed for each rectifier to achieve a first charge and recharges (in other words, the times needed to have the first measurement and transmission, and between each next ones), as well as their available output voltage, in function of the available RF input power at 868 MHz. These rectifiers are characterized at 868 MHz which is within a few MHz of their optimum use value. Concerning the output voltages: the Rect1 ones are the highest whatever the input RF power, but the Schottky diodes saturate for powers higher than +6 dBm; and the Rect2 ones are lower than the Rect3 ones, which is justified by the fact that Rect2 was designed with size as a priority and Rect3 with efficiency as priority. Because of this design rule, Rect2 is less efficient than Rect1 and Rect3 with larger first charge and recharge durations. During the cold-start procedure (the main part of the first charge duration), a less than 400 mV voltage is imposed by the PMU, that why Rect3 is faster than Rect1 (which is more efficient for higher voltages) for the first charge. In contrary, when the cold-start procedure is achieved, Rect1 is faster than Rect3 for highest RF input powers, but the two rectifiers are close similar for lowest RF input powers. Regardless of the chosen rectifier, the SN have a periodicity of measurement and transmission which variate between few minutes to hours in function of the available power. Thus, by controlling the RF power source (in terms of transmitted power or duty cycle) it is possible to control wirelessly this periodicity without alter the SN software or hardware parts.

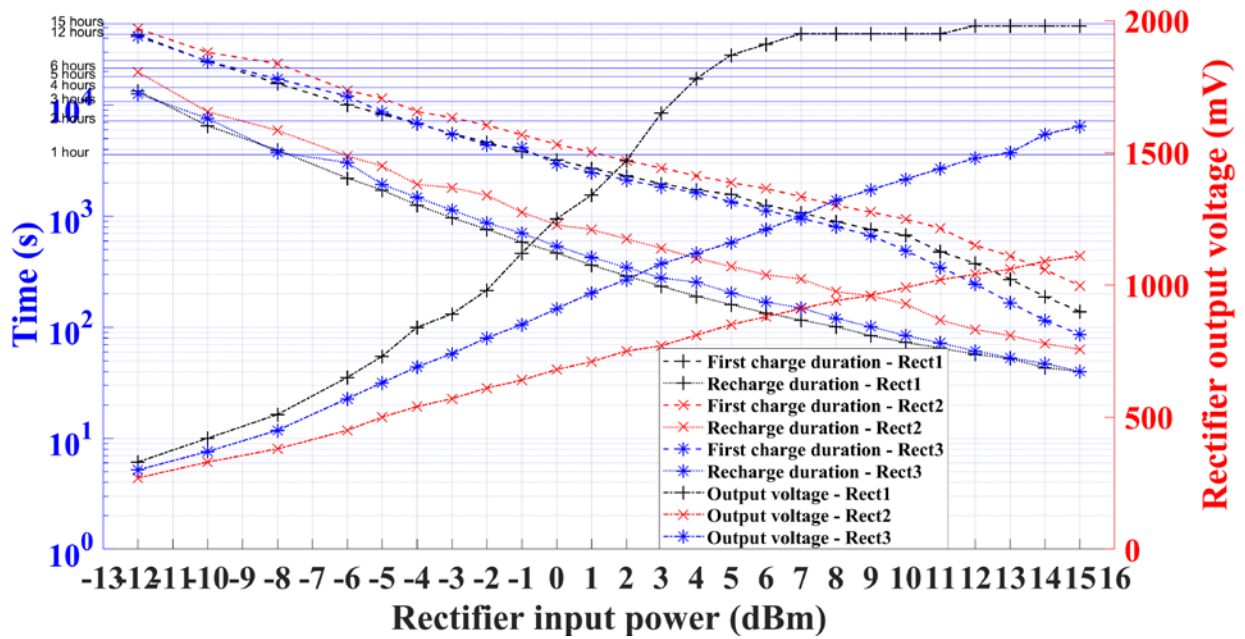


Fig. 5. Durations of the first charge (dashed lines, left) and recharges (dotted lines, left) and rectifier output voltages (dotted and dashed lines, right) as function of the controlled RF power at 868 MHz applied at the input of the rectifier of the sensing nodes for the various rectifiers under test: Rect1 (+), Rect2 (x) and Rect3 (*).

Nevertheless, the energy efficiency of the SN (here defined as the ratio of the energy available at the input of the rectifier (i.e. the integrated available RF input power over the period of interest) to the energy needed for a measurement and transmission) is rather low for the first charge (between 3.4% and 9.2% for Rect1, 2.3% and 7.7% for Rect2 and 4.7% and 9.2% for Rect3) and recharges (between 13.1% and 36.4% for Rect1, 8.3% and 21.7% for Rect2 and 13.1% and 31.0% for Rect3), as shown respectively in Fig. 6 and Fig. 7. As said earlier, Rect3 is more efficient than Rect1 during the first charge whilst this is the opposite during the recharges. For all the rectifiers, the lowest efficiencies during the first charges are for input powers higher than +4 dBm. Only Rect3 sees this efficiency re-increasing for input powers higher than +12 dBm. Moreover, the lowest efficiencies during the recharges are for lowest and highest input powers. To improve this energy efficiency, the electrical losses and the needs in terms of energy must be limited. For instance, the used supercapacitor has losses up to 11.5 μW for a 2.30 V voltage and up to 22.3 μW for a 4.45 V voltage. As well, the needed energy by the SN can be minimized by optimizing the software to shorten process time, by choosing low consumption sensors and transceivers, etc. In this way, the capacity could be reduced, as well as activation and deactivation threshold voltage, and so the losses could be again limited. Also, developing specific and well-defined components could improve the efficiency by reducing the needed energy: for instance, the PMU used needs at least 15 μW just to work. Last but not least, the development of high efficiency rectifier (or RF-to-dc converter) has a large impact on the energy efficiency. In spite of these weak efficiencies, the SN are usable thanks to the data that can be generated and transmitted periodically, nevertheless this criterium has to be take in consideration to provide a sustainable system.

The PCB (14 cm x 9 cm) dedicated to the SN was designed in order to be used as a reflector plan for the rectenna to increase its efficiency and the amount of harvested energy. Even if it was the rectenna presented in [16] (with Rect3) which was first chosen for the SN, the one presented in [14] (with Rect1) was finally privileged because of a higher efficiency and compactness (from 11 cm x 6 cm x 3 cm to 6 cm x 3.5 cm x 1 cm), despite a lower gain of the antenna (from +6.6 dBi to +5 dBi). This choice will allow to decrease the volume of the SN which is constraint by the antenna and supercapacitor sizes. As presented in Fig. 8, there are good correlations for the duration of the recharges and the output voltage of the rectifier between the SN powered through the rectifier by a controlled RF power and the SN wirelessly powered in the air which scavenges the RF power transmitted by the CN, in the cases of input powers higher than +2 dBm. For lower powers, there are more differences which can be explained by approximations during experiments and in the estimations of the RF power density illuminating the rectenna, but also by the impedance de-adaptation between the rectifier and the antenna which induces an efficiency of the rectenna different than 1, as well as the multipath effects. For these measurements, the SN was located in the air at a distance between 60 cm and 300 cm to the power source and were achieved with a 20 cm step. In spite of these observations, we estimate that the maximal distance between the CN and the SN for the WPT should be higher than 5 meters.

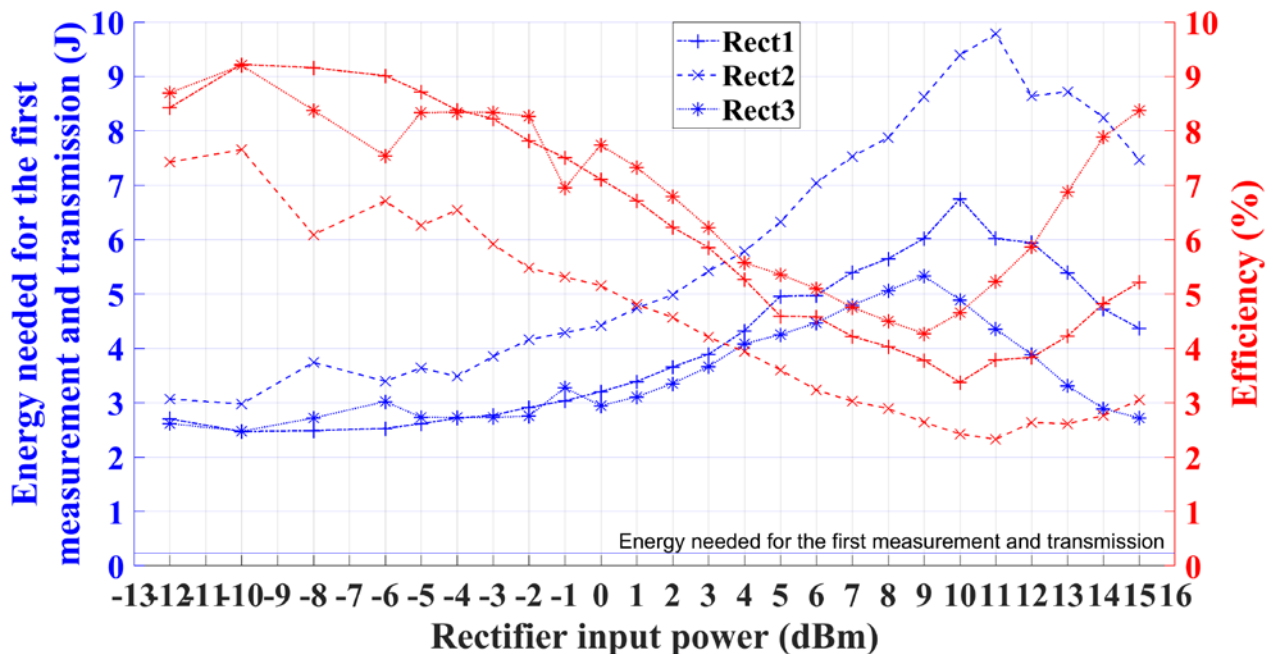


Fig. 6. Energy needed for the first charge (blue) and the energy efficiency of the SN during this first charge (red) as function of the controlled RF power at 868 MHz applied at the input of the rectifier of the sensing nodes for the various rectifiers under test: Rect1 (+), Rect2 (x) and Rect3 (*).

To complement these quantitative tests, several qualitative tests were achieved. A network architecture with a unique CN and multiple SN was tested in the air in order to certify that several SN can be powered by the same CN in a specified area and that the data sent by each SN is well received and processed by the CN. As presented in Fig. 9. A., a SN embedded in a reinforced concrete beam has successfully be wirelessly powered by a CN located 170 cm away to which it sent successfully all the measured data. This 170 cm are composed of 15 cm of reinforced concrete and 155 cm of air. A specific air cavity was designed in the reinforced concrete beam to achieve these tests which are encouraging with the aim of provided a communicating reinforced concrete. Finally, as for the CN, initial tests using an Aerotek C11-1FFF/OPT.N circulator between a monopole antenna (port 1), the rectifier input (port 2) and the LoRaWAN transceiver output (port 3) were successfully achieved: a SN at 60 cm and 160 cm from the CN antenna has be wirelessly powered by it and transmitted it all its measured data. In this way, it is possible to use a unique antenna in the SN and reduce its size.

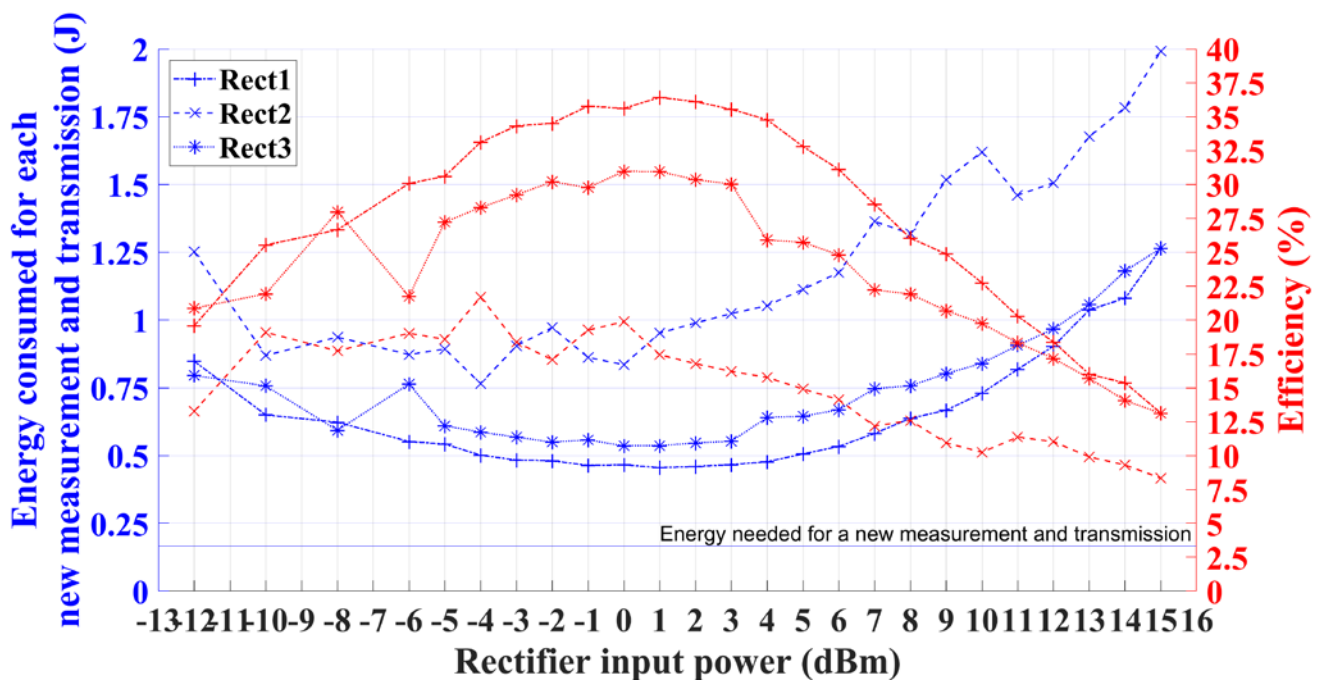


Fig. 7. Energy needed for recharges (blue) and the energy efficiency of the SN during recharges (red) as function of the controlled RF power at 868 MHz applied at the input of the rectifier of the sensing nodes for the various rectifiers under test: Rect1 (+), Rect2 (x) and Rect3 (*).

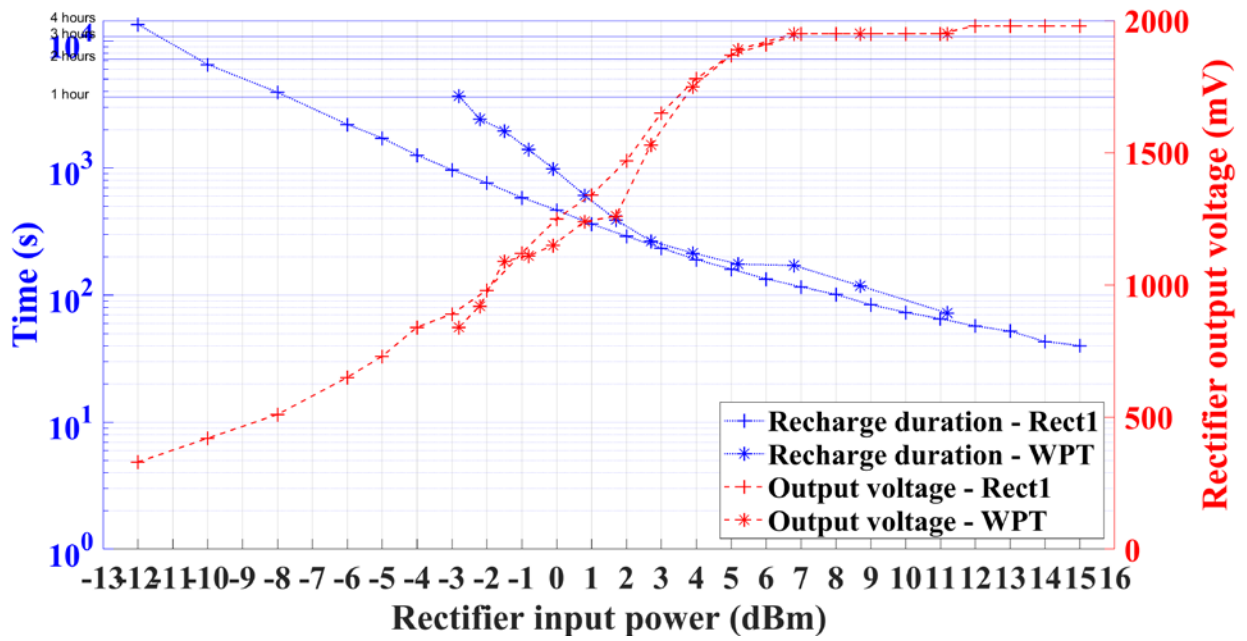
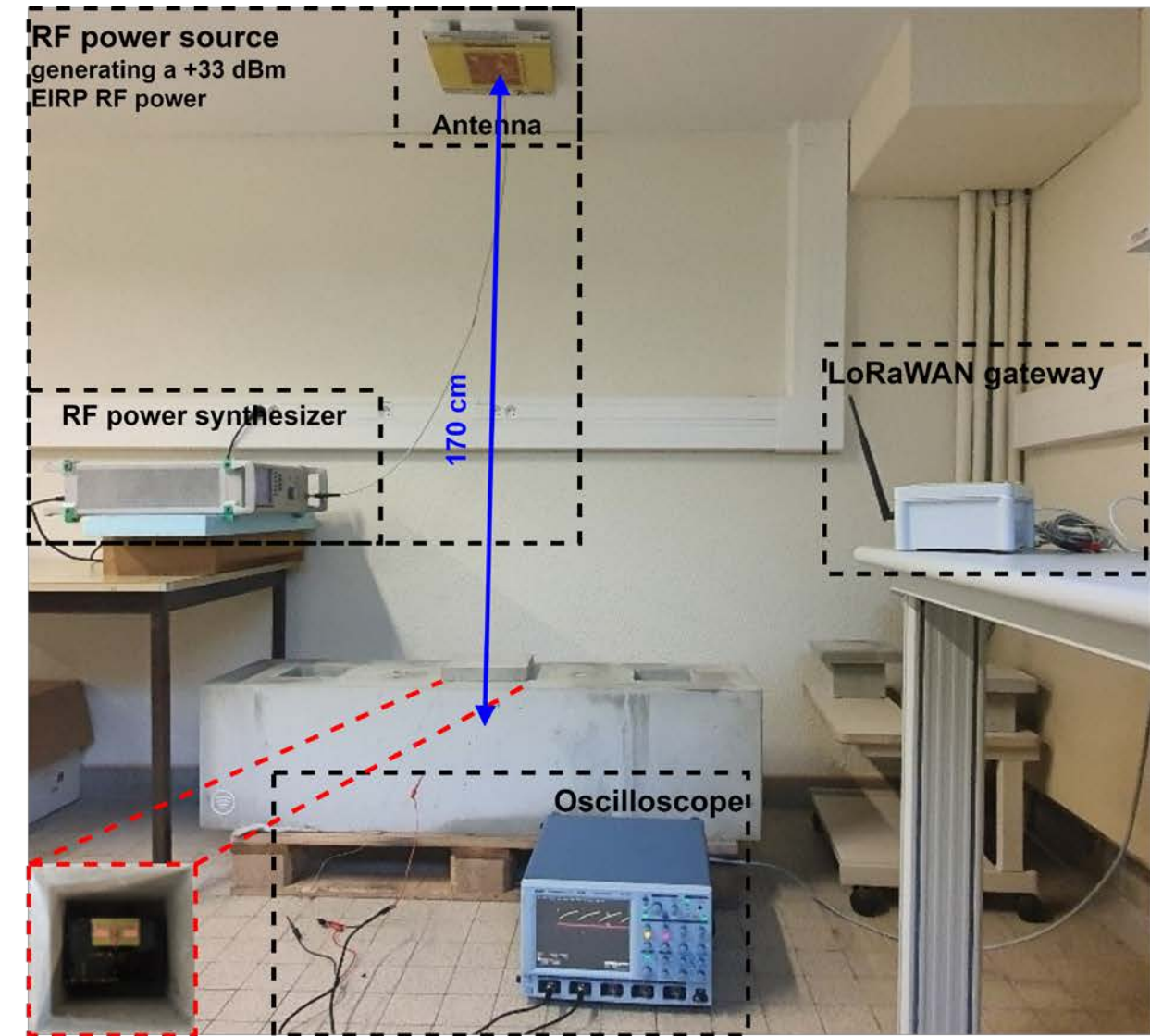


Fig. 8. Duration of the recharges (blue dotted lines) and rectifier output voltages (red dashed lines) as function of the RF power at 868 MHz at the input of the rectifier of the sensing nodes for the single rectifier Rect1 (+) and the rectenna (*).



Sensing Node

(A) (B) (C)

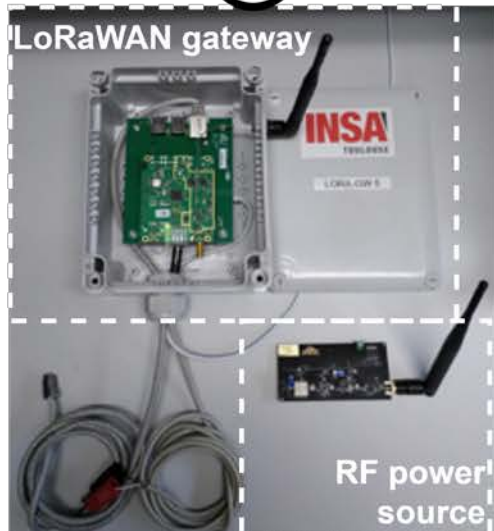
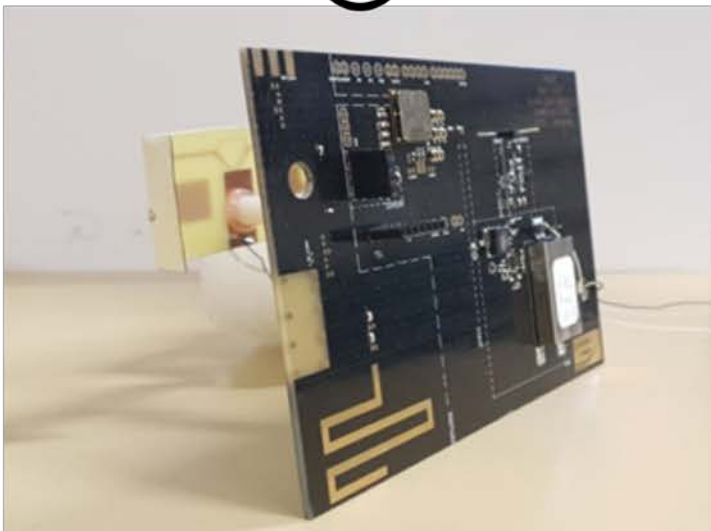


Fig.9 Photograph of (A) the qualitative test achieved with a sensing node embedded into a reinforced concrete beam, (B) the Sensing Node and (C) the Communicating Node.

V. STATE OF PROGRESS / CONCLUSION

A wireless sensor network was designed and implemented in order to be fully embedded into reinforced concrete able to monitor itself during its entire life. The first prototypes of sensing nodes and communicating nodes have been designed, implemented and fully characterized. Their tests confirm a fully ability of functioning. The communicating nodes, composed of a LoRaWAN gateway and a RF power source, are able to receive, process, store and provide to the final user (through the Internet or a direct link) the data collected and transmitted by the sensing nodes. They are able to wirelessly power these sensing nodes and wirelessly control their periodicity of measurement and transmission through a far-field wireless power transmission system. The fully wireless and battery-free sensing nodes are, themselves, able to sense temperature and humidity, pre-process the measured data and send them wirelessly -via LoRa technology and LoRaWAN protocol - to the communicating nodes. Several experiments in the air and in a reinforced concrete beam suggest that a unique communicating node could power, control and manage tens to hundreds sensing nodes located in an area of few meters around it.

Global architecture

The current architecture is composed of:

- Sensing nodes, powered by far-field radiofrequency wireless power transmission which can make measurements and wirelessly transmit the collected and processed data.
- Communicating nodes, which can retrieve the data send by the sensing nodes and transmit it to relocated dedicated servers; and wirelessly power the sensing nodes, and thus wirelessly control their periodicity of measurement and transmission.
- Dedicated servers, which collect, store and process all the data harvested by the communicating nodes to be made available to users.

Sensing nodes

They are:

- Compact (8 cm x 6 cm x 5 cm)
- Energy autonomous because battery-free and wirelessly powered by a far-field radiofrequency wireless power transmission over several meters (in a reinforced concrete beam and/or in the air), thanks to a dedicated WPT interface (rectenna, PMU, supercapacitor and DC-to-DC buck/boost converter)
- Able to measure and process various parameters (temperature, and/or humidity, but also mechanical deformation (works in progress) and concrete resistivity (works in progress)) thanks to various sensors (off-the-shelf temperature and/or humidity sensor, Cambridge thermodiodes,

stress gauges (works in progress), LMDC resistive sensor (works in progress)), available through hardware plug-ins and a reconfigurable software platform.

- Able to wirelessly communicate the collected and processed data to the communicating nodes through LoRaWAN and Bluetooth Low Energy (works in progress) protocols.
- Wirelessly controllable by the communicating nodes in terms of periodicity of measurement and transmission by the tuning of the transmitted RF power.
- Able to use a unique antenna both for the WPT and the wireless communication thanks to a RF circulator and the use of the 868 MHz ISM band for the both technologies (in the case of LoRaWAN, but for BLE a similar approach can be possible in the 2.45 GHz ISM band).

Communicating nodes

They are composed of two elements: a gateway and a RF power source; which are currently independent. Nevertheless, it is possible to interconnect them especially in order for the gateway to control the RF power source.

The RF power source:

- Wirelessly powers by a far-field radiofrequency wireless power transmission a lot of sensing nodes located in an estimable volume.
- Uses a +33 dBm continuous wave scheme (other schemes as pulses or chirps are under investigation) in the 868 MHz ISM band (other ISM bands are usable but specific constraints must be taken into consideration (e.g. maximal EIRP which induce the maximal useful distance, etc.)).
- Can be used in order to wirelessly control the periodicity of measurement and transmission of the sensing node by the tuning the power and/or the duty-cycle of the wave.

The gateway (LoRaWAN case, for the BLE case the work is still in progress):

- Can retrieve the data send by a lot of sensing nodes located around.
- Can process and store locally the collected data.
- Can transmit the collected and processed data from the sensing nodes to relocated dedicated servers through the Internet, in order to store and make it available worldwide for the various users.
- Are locally accessible through an Ethernet or WiFi connection.

Proof of concept of the fully operating WSN

Currently, we are able to generate and wirelessly transmit -through LoRaWAN- temperature and/or humidity data from several sensing nodes -located in a reinforced concrete beam or in the air and which are fully wireless and wirelessly powered over several meters by dedicated RF power sources located in

the communicant nodes-, to a network of two communicating nodes. These communicating nodes are connected to each other by WiFi and only one is connected to the Internet and allows to transmit all the data (collected by the two communicating nodes) to the relocated and dedicated servers. Each communicating node process and stores locally the collected data, and are accessible locally through an Ethernet or a WiFi interface. The servers process, store and make available the data to the users though the Internet.

VI. RECONFIGURABILITY ASPECTS

Reconfigurability of the sensing nodes

The configuration of the sensing nodes is made during their manufacturing by choosing the appropriate hardware parts (through various daughter boards (e.g. power management unit, supercapacitor, antenna, rectifier, sensor(s), transceiver and microcontroller unit)), the configuration of the power management unit thresholds (for activation and deactivation of the powering of the active elements through the discharge of the supercapacitor), and the appropriate software (e.g. unique identifier(s), security key(s), kind of wireless communication protocol, kind of sensor(s) and associate on-board communication protocol, etc.).

Because of the conception choices, there is no real reconfigurability of the sensing nodes. Indeed, once deployed the sensing nodes become inaccessible (Neither the hardware nor the software can be modified or replaced, and these must work for the entire lifespan of the reinforced concrete element in which they are embedded. As well, the wireless communication technology must be maintained during all the lifetime of the sensing nodes.). Moreover, no downlink is implemented in order to limit as far as possible the energy needs and to close all the back doors for preventing malicious attacks. In that way, there is no way to communicate with the sensing nodes and remotely software updates are no more possible.

Nevertheless, the communicating nodes can wirelessly control the behavior of the sensing nodes located in their neighborhood. The sensing nodes are developed in order to have a simple functioning: they scavenge radiofrequency energy until having enough energy to start-up, measure targeted parameter(s), pre-process and wirelessly broadcast the collected data to the communicating node, and then they consume the full residual energy by trying to re-achieve all these steps. In that way, the periodicity of the operation of the sensing nodes (measurement and uplink transmission) can be wirelessly control by the communicating node by controlling their embedded radiofrequency power source or, in other words, by tuning the amount of power transmitted to the sensing nodes. This control can be made by tuning the

duty-cycle of the powering of their radiofrequency power source or by tuning the power delivered by their radiofrequency power source.

To go further and to upgrade the power efficiency and the security, a learning period can be useful in order to characterize the environment of each communicating node, *id est* to discover the legal sensing nodes located in its neighborhood, to know their needs in terms of power to send for fully charging them (e.g. for a continuous wave at a specified transmitted radiofrequency power, the times need for the first charge and the recharges, etc.) or even their location by implementing beamforming solutions in the communicating nodes. It is even conceivable to make cohabite several fleets of sensing nodes (e.g. embedding different kinds of sensor) by dedicating a specific radiofrequency sub-band for the wireless powering to a kind of sensing nodes or even to a specific sensing node, or once more, by using beamforming solutions.

Reconfigurability of the communicating nodes

The communicating nodes could be reconfigured and upgraded during all their lifetime thanks to their physical accessibility (they are located on the surface of the reinforced concrete element) and the various available bidirectional communication interfaces (e.g. a wire programming interface, short-range wireless interface for a local user access (if implemented), between communicating nodes wireless interface, the Internet interface (from the BIM or other), etc.).

For the hardware, it is conceivable to change or add parts (e.g. change the entire communicating node, change a battery, change the microcontroller unit, add memory, add a new wireless communication interface, upgrade a wireless communication interface (e.g. from [n]-G to [n+1]-G), repair the radiofrequency power source, etc.). Nevertheless, the wireless communication interface with the sensing nodes must be maintained in order to assume their functioning during all their lifespan. Thus, the use of a personal and self-administered network could be privileged in order to certificate a long-term use. Third-part network could need to be upgraded or stopped and become incompatible with the initial needs.

For the software, the reconfigurability and the updates could be achieved by various stakeholders and on different ways. Indeed, there exists several bidirectional communication interfaces: from wire programming interface (in case of a direct access), to the Internet connection, through the in-between communicating nodes interface (or even others). The software modifications could affect different aspects of the network: the periodicity of the measurements of the sensing nodes (through the control of the radiofrequency power sources), the kind of measurements (in case of different fleets of sensing nodes independently controllable), the processing of the collected data, some on-board processing, the managing of memory, the routing protocol in the communicating nodes network, the affectation between the communicating node of the Internet gateway role, etc. These modifications can be provided by a specific

stakeholder or come from the BIM or another digital ‘decision-makers. It must be noted that the current communicating nodes using LoRa or Bluetooth Low Energy embed an operating system (respectively ChirpStack Gateway OS and FreeRTOS) and several tools.

To go further and to upgrade the power efficiency and the security, a learning period can be useful in order to characterize the environment of each communicating node, *id est* to discover the legal sensing nodes and communicating nodes located in its neighborhood and even their location by implementing beamforming solutions, to know the needs of the sensing nodes in terms of power to send for fully charging them (e.g. for a continuous wave at a specified transmitted radiofrequency power, the times need for the first charge and the recharges, etc.), and to define the rights for each stakeholders (e.g. the bidirectional communication interfaces they can use, the kind of modifications they can make, etc.) as well as backup solutions. Anyhow, energy efficiency and security aspects must be taken into consideration before opening the network.

VII. PERSPECTIVES

A new version of the SN with an integrated rectifier is being designed in order to get a more compact and more efficient SN. The integration of a RF circulator is under consideration in the aim to use a unique antenna in the SN. Works on more efficient rectenna are always pursued too.

Lastly, first tests of BLE communication -in master/slaves and broadcasters/listener topologies- into the reinforced concrete beam was performed by using NXP QN9080DK development board. Communication distance of 20 meters can be reached with a board embedded in the reinforced concrete beam even if first packet errors appear from nearly 10 meters. It was also possible to achieve lossless communication between two boards embedded in the reinforced concrete beam at a distance of around 90 cm. Nevertheless, there is no evidence to support that communications took place only in the reinforced concrete, maybe another path (through reinforced concrete and air, with a reflection on the ground) has been followed.

Regarding the communicating nodes, the design and manufacture of a one-part and compact version will allow gains in terms of compactness, energy consumption and efficiency. Also, alternatives to the CW RF power source -as pulses RF power source- are studied with the aim to increase the WPT efficiency and decrease the energy consumption.

Regarding the sensing nodes, other kinds of sensor relevant in the case of SHM of reinforced concrete structures -e.g. strain gauges, corrosion sensors, etc.- are searched in order to be integrated in prototypes. More energy efficient components -e.g. supercapacitor, LoRaWAN transceiver, etc- are wanted too. SN

prototypes with a BLE communication solution could be interesting in order to have the same order of magnitude between the useful distance of WPT and communication, and to provide a solution needing less energy.

In order to ensure the energy autonomy of smart nodes, various strategies can be employed as those proposed in the diverse implementations of battery-free LoRaWAN nodes provided in the past years. Some harvest ambient energies (e.g. solar or thermal [17], mechanical [18], etc.), others are based on backscattering of LoRa signal [19], but although the feasibility of powering LoRaWAN nodes by WPT was demonstrated theoretically in [20], at our best knowledge no full implementation was provided until [15]. By using WPT, the nodes are no more dependent of the availability of ambient energy sources and, by controlling the RF power source, the wireless control of the measurement and transmission periodicity is possible without software or hardware changes.

The majority of the actual wireless and battery-free nodes uses the RFID technologies, which allow short-range communications based on backscattering. These technologies are, for instance, used for SHM applications through active tags [21] or tags intrinsically able to quantify a physical parameter [22]. Nevertheless, implementations based on WPT were proposed too, as in [23] which used short range near-field (or inductive) WPT and M-BUS medium range communication technology, or in [24] which used medium range far-field WPT and BLE medium range communication technology. Equally, solutions based on RF far-field EH were developed, as in [25] but at the cost of a large system.

Anyhow, at our best knowledges, this is the first WSN fully embedded into reinforced concrete and composed of fully wireless sensing nodes wirelessly powered and controlled by a WPT system, dedicated to the SHM of the material during all its lifetime.

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